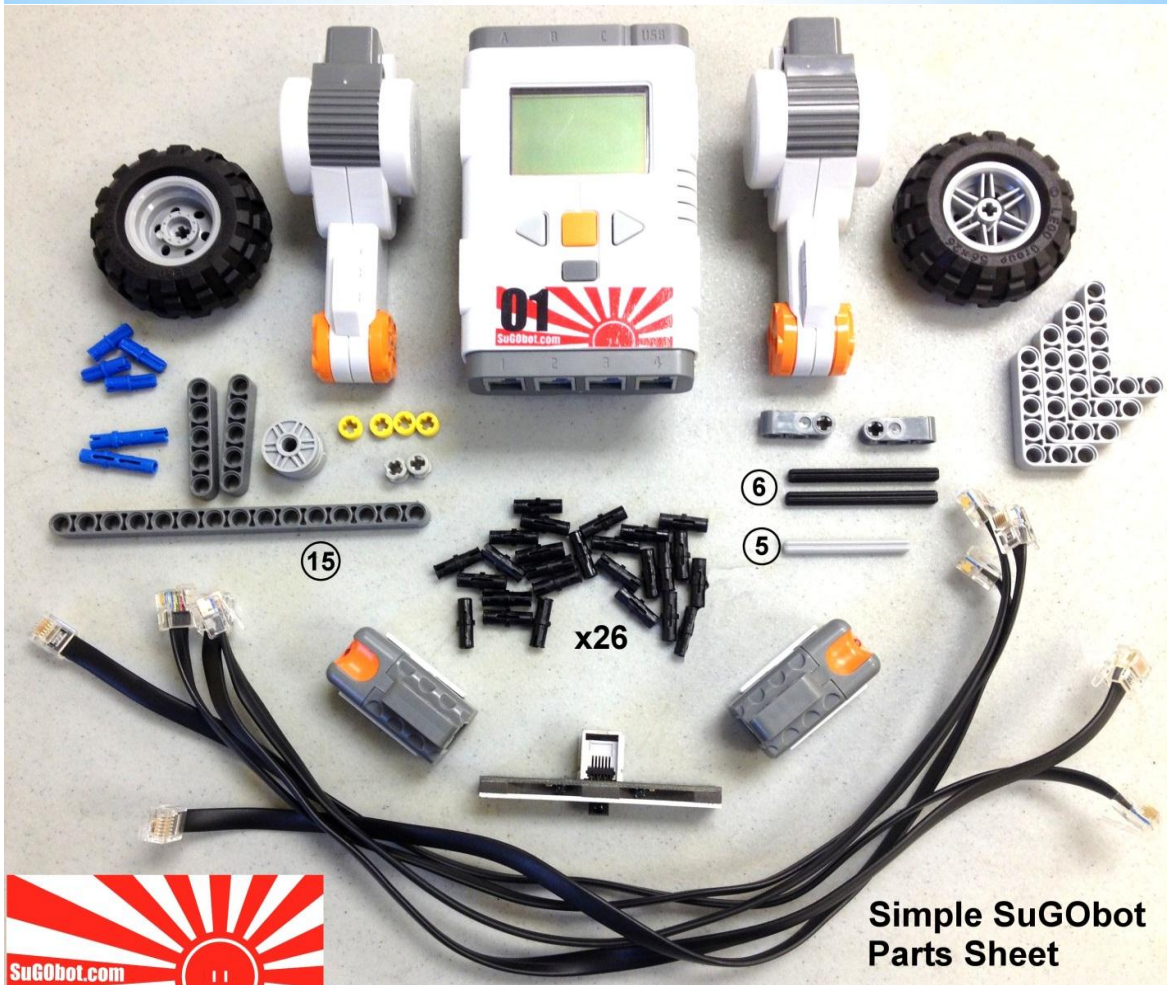




* Simple SuGOBot

by Mr. Phil



Step 1



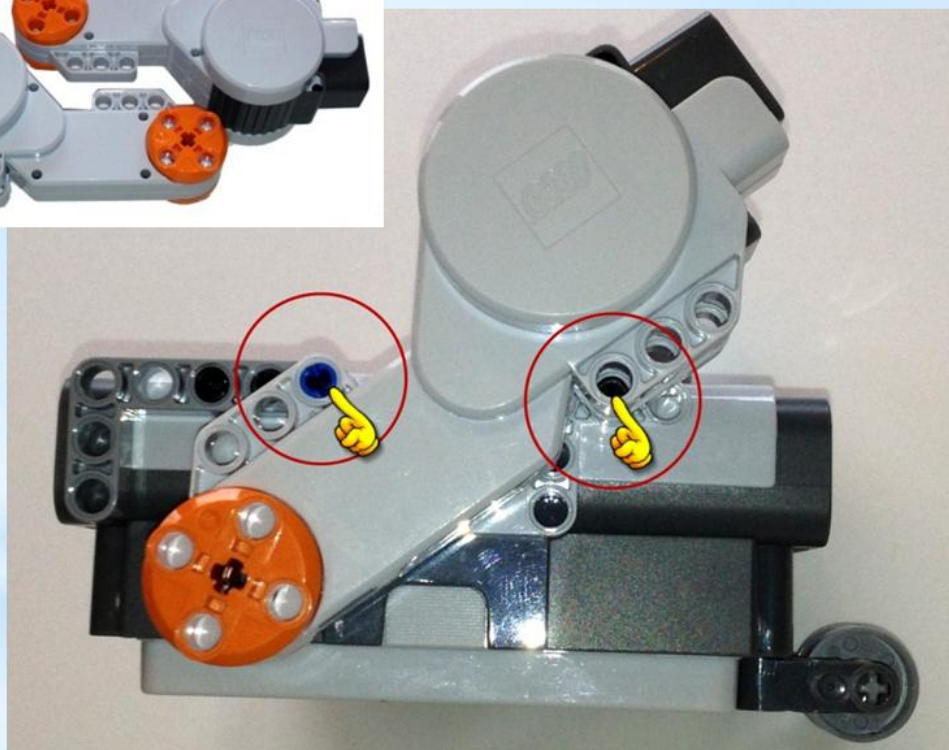
Step 2



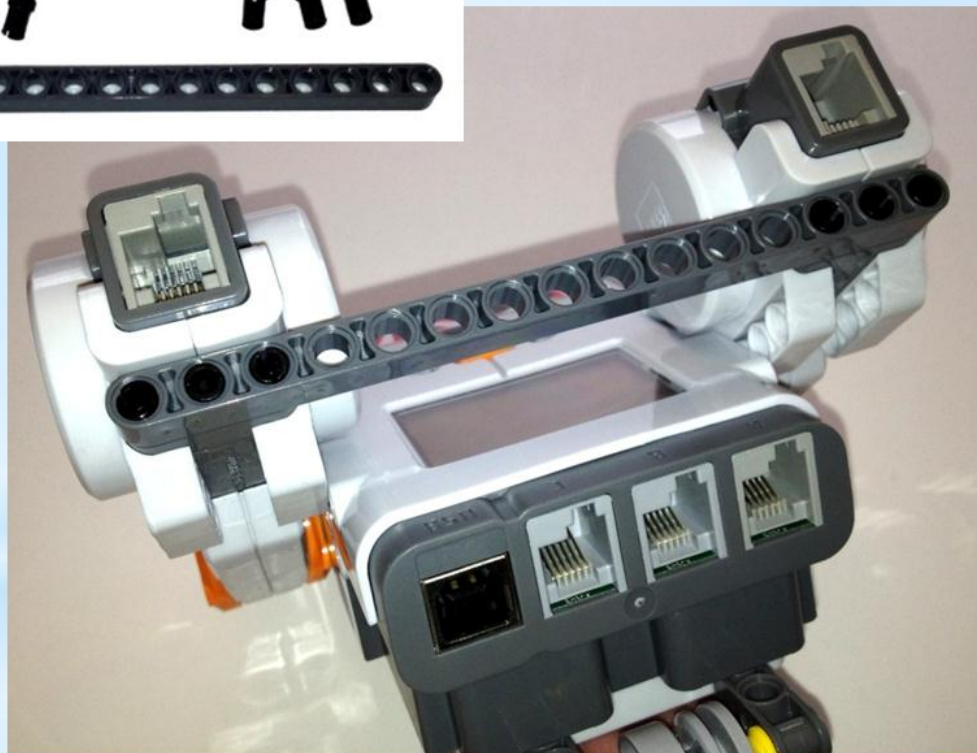
Step 3



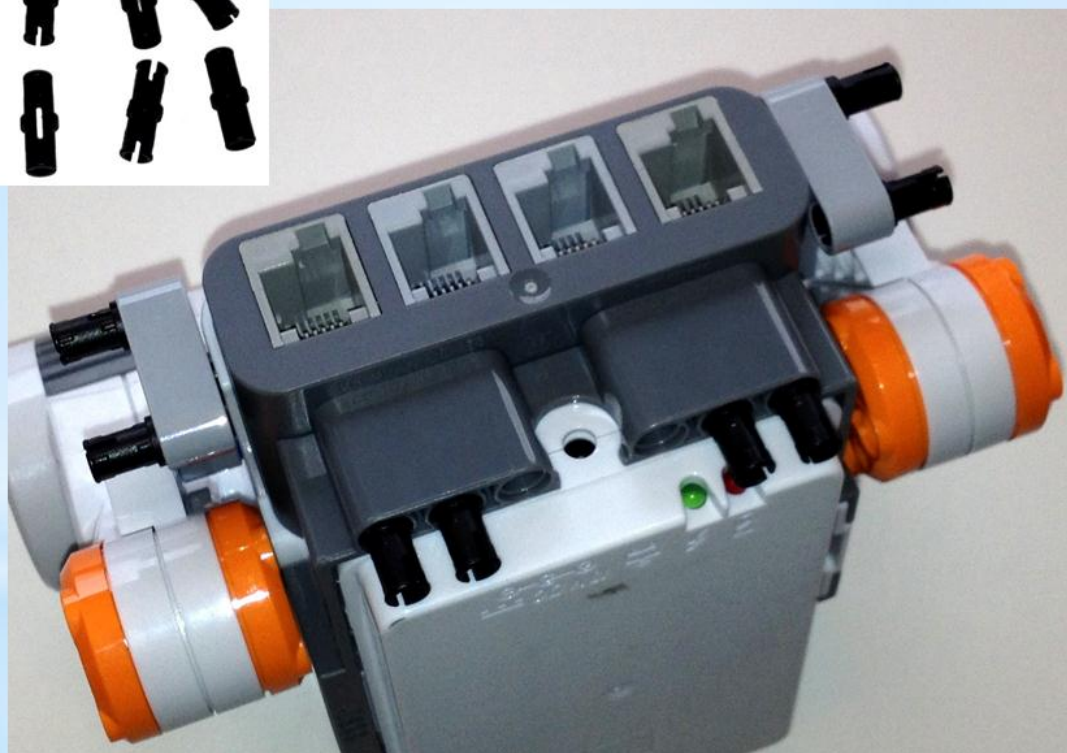
Step 4



Step 5



Step 6



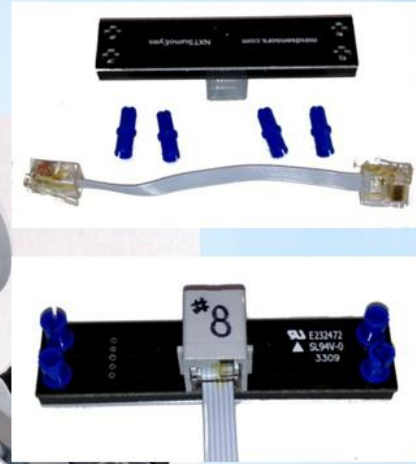
Step 7



Step 8



Step 9



Step 10



Step 11

Inputs

- Left Line Sensor: Port 4
- Right Line Sensor: Port 1
- SumoEyes: Port 2

Outputs

- Left Wheel: Port C
- Right Wheel: Port A

